EPICS Deployment at Sigray using Docker

SIGRAY

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Founded in 2013

 Dr. Wenbing Yun (OSA Fellow and serial entrepreneur that founded Xradia, now Carl Zeiss X-ray Microscopy) and Sylvia Lewis

Our Technology:

- Strong IP: 64 patents, 30+ pending, many trade secrets
- Disruptive x-ray components (source & optics)
- 5 world leading product families

Rapidly Growing:

- 34k sq. ft. facility in Concord, CA (San Francisco Bay Area) and 82 employees
- Global installation base of leading universities and companies (semiconductor & pharma)

Refer to <u>Benajmin Stripe's presentation</u> for more information.



Intro to Sigray

Mission: Bring next-generation x-ray analytical capabilities from the synchrotron to the laboratory



Contents

- Motivation
- Technologies
- How it works
- Usage
- Deploying updates
- Takeaways



Motivation

The pre-existing setup

- A machine has multiple devices, each controlled with an EPICS IOC
- IOC settings may be different between machines
 - Differences can include what db, template, or iocsh files are called, environment settings, IP addresses, etc.
 - Difficult to maneuver IOCs to allow us to do this natively
- We already had dockers for each IOC
 - Each docker had its own folder
 - Not in version control
- Difficulties
 - Hard to know what dockers are existed
 - Hard to track the configuration differences between machines
 - This leads to making it hard to identify and propagate fixes that were made on one machine and not others
 - Hard to reproduce a machine

Motivation

We wanted to ...

- Track the configuration of machines after shipment to be able to reproduce the machine
 - Set up new machines
 - Reinstall dockers if a computer fails
 - Debug issues with shipped machines
- Make it easy to share fixes and feature updates across all machines
 - Can involve changing synApps module versions, manual fixes to IOC source code via docker, system startup service scripts, etc.
- Standardize shared configuration to make debugging and setup easier
 - Ports, IP addresses, paths
- Allow offline updates (and builds) due to customer restrictions
- Make it easy to create new IOCs



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Motivation

Who would be the user?

- A mix of users
 - Non-Linux users unfamiliar with a terminal or bash
 - Varying ranges of familiarity with Python and docker
- Controls engineers and software engineers
 - \circ $\,$ Add new IOCs and docker services
- Systems engineers
 - Customize files for the system (e.g. hdf5 xml files for areaDetector and db files)
- Field service engineers
 - Perform updates
 - Reload autosave files

Technologies

🕑 • Docker

- Allow conflicting dependencies
- Freeze dependencies
- Easy to deploy
- Docker Compose
 - Allow inheritance of docker service definitions
 - Can define multiple dockers and their build and run settings in one file
- Portainer
 - Docker management
- Procserv
 - Wrapper for running IOCs as background processes with telnet access

- Bash
 - Helper scripts
 - Easier to call most commands directly
- **e**.
- Helper scripts and GUI
- Will replace most of the bash scripts because it's more readable and easier to debug
- Poetry

Python

- Python dependency manager
- Tests
 - Bats framework for bash tests
 - pytest for everything else



CIDER

Overview

- Configuration, Installation, and Deployment of EPICS Repositories
- Basic idea
 - One repository to store all docker-related files and machine configuration files
 - Have one base docker image for online dependencies
 - Mostly installing synApps modules with assemble_synApps.sh
 - Each IOC docker image builds on top of the base docker image and includes no online dependencies at build time
 - Each machine mounts its own set of files at runtime, overwriting existing IOC files
 - Use environment variables and inheritance to avoid code duplication
- Allows us to:
 - View existing docker services for IOCs (and other utilities) and add them for specific machines
 - Make and track modifications to the IOCs per machine
 - Standardize values in an environment file and propagate them to all dockers



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CIDER

File Structure Example

- components/
 - component_a/
 - common-services.yml
 - compose.yml
 - Dockerfile
 - common/
 - variation_1/
 - **...**
- ioc_submodules/
- machine_compose_files/
 - compose.am-1124.yml

• environment_files/

- common_env_vars
- am-1124.config

rf1-attomap-310:	
container_name: xr	f1
<pre>image: sigray/iocs</pre>	/xrf1/attomap-310:\$TAG
extends:	
file: \$CIDER_REP	O/components/sigray_base/common-services.yml
service: common-	base-container
build:	
context: \$CIDER_	REPO/components/xrf1/attomap-310
additional_conte	xts:
iocs: \$CIDER_R	EPO/iocs
dockerfile: \$CID	ER_REPO/components/sigray_base/Dockerfile.xrf1
environment:	
EPICS_CA_SERVE	R_PORT: \$PXM1_PORT
NUM_OPTICS: \$N	UM_OPTICS
SOURCE_Z_DIREC	TION: \$SOURCE_Z_DIRECTION
volumes:	
# Runtime settin	<i>qs</i>
- \$IOC DATA/xrf1	/autosave:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/autosave
- \$IOC DATA/xrf1	/iocInfo:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/iocInfo
# Variation sett	
- \$CIDER REPO/co	<pre>mponents/xrf1/\$MOTION_VARIATION/st.cmd:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/st.cmd</pre>
	<pre>mponents/xrf1/\$MOTION_VARIATION/auto_settings.req:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/auto_settings.req</pre>
command:	
1	
"bash",	
"-c".	
"/opt/epics/st	art_iocs/start_xrf1.sh; /bin/bash"
1	
,	
	xrf1:
	container name: xrf1

extends: file: ../components/sigray_base/compose.yml service: xrf1-attomap-310



CIDER

LIDEK	xrf1-attomap-310:			
	container_name: xrf1			
File Structure Example	<pre>image: sigray/iocs/xrf1/attomap-310:\$TAG extends:</pre>			
The Structure Example	file: \$CIDER_REPO/components/sigray_base/common-services.yml			
	service: common-base-container			
 components/ 	build:			
	<pre>context: \$CIDER_REPO/components/xrf1/attomap-310 additional_contexts:</pre>			
 component_a/ 	iocs: \$CIDER REPO/iocs			
	<pre>dockerfile: \$CIDER_REPO/components/sigray_base/Dockerfile.xrf1</pre>			
 common-services.yml 	environment:			
-	EPICS_CA_SERVER_PORT: \$PXM1_PORT			
compose.yml	NUM_OPTICS: \$NUM_OPTICS SOURCE Z DIRECTION: \$SOURCE Z DIRECTION			
	volumes:			
 Dockerfile 	# Runtime settings			
	 \$IOC_DATA/xrf1/autosave:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/autosave 			
common/	 \$IOC_DATA/xrf1/iocInfo:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/iocInfo 			
	# Variation settings			
variation_1/	 \$CIDER_REPO/components/xrf1/\$MOTION_VARIATION/st.cmd:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/st.cmd \$CIDER_REPO/components/xrf1/\$MOTION_VARIATION/auto_settings.req:/opt/epics/synApps/iocs/xrf1/iocBoot/iocxrf1/auto_settings.req 			
	command:			
■ ····	"bash",			
 ioc_submodules/ 	"-c", "/opt/epics/start iocs/start xrf1.sh; /bin/bash"			
 machine_compose_files/ 				
· maenine_compose_mes/	xrf1:			
 compose.am-1124.yml 	container_name: xrf1			
	extends:			
 environment_files/ 	<pre>file:/components/sigray_base/compose.yml</pre>			
	service: xrf1-attomap-310			
 common env vars 				

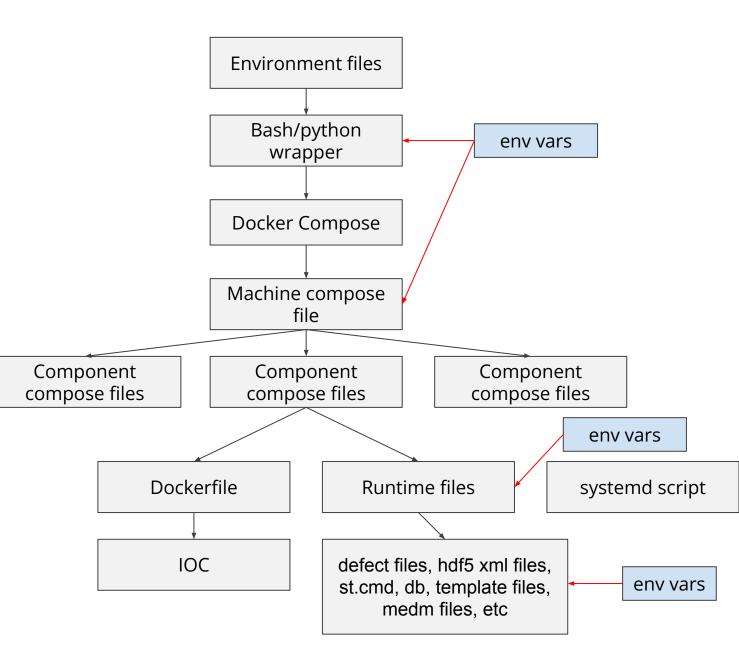
• am-1124.config

CIDER

Machine Callgraph

The machine is configured using:

- Environment files dictate:
 - Machine compose file
 - What paths are mounted
 - IOC settings (e.g. sequencer, st.cmd, .db. etc)
- A machine compose file to dictate what IOC dockers it uses
 - Simply extends component definitions to reduce code duplication
- Docker bind mounts to overwrite specific IOC files



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Control turf grass imaged on Sigray AttoMap. Potassium (green), calcium (red), manganese (blue) at 20 micron step sizes.

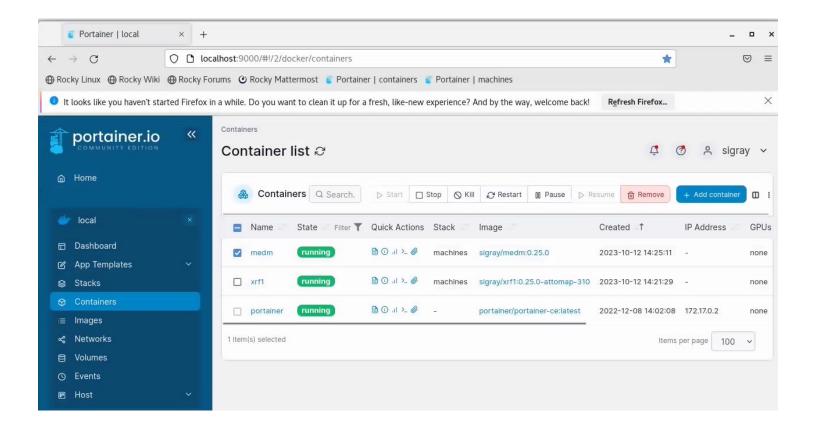


Machine setup

- Set up new machines
 - Set up udev rules (for serial-specific devices) and network settings
 - Create configuration files
 - Build and run docker services
 - Save settings
 - Autosave files
 - OS version
 - udev rules
 - Network configuration
- Total setup time: 30-60 minutes (including build time)
 - Assuming there aren't any new devices or issues
 - Not including Jenkins and PRs

Tools - Portainer

• Use Portainer to restart the dockers/IOCs with updates





Tools - GUI

- Easy access to files for system engineers
- Rebuilding dockers and recreating containers
 - Portainer does not quite have this feature

		CIDER
Machine Components	Select a machine am-1132	Medm Qd Qd-calibrate Sigray-base Sigray-iocs Xrf1
	View Mode	Medm
Machine Configuration Generate USB Rules Autosave	Dockers	Predm Container Name medm Image Tag sigray/iocs/medm:0.51.10 Docker Compose File /home/htruong/Desktop/cider-dockers/components/sigray_base/compose.yml Open File Common Docker Compose File /home/htruong/Desktop/cider-dockers/components/sigray_base/common-services.yml Open File Dockerfile /home/htruong/Desktop/cider-dockers/components/sigray_base/common-services.yml Open File Dockerfile /home/htruong/Desktop/cider-dockers/components/sigray_base/Dockerfile.medm Open File Build Folder /home/htruong/Desktop/cider-dockers/components/sigray_base/service.sh Open File Build Folder /home/htruong/Desktop/cider-dockers/components/sigray_base/service.sh Open File Build Folder /home/htruong/Desktop/cider-dockers/components/medm/common Open File Build Files Type Date Modified Type Name Local Path Size Type Date Modified > all_adl /home/htruo 44.00 KiB Folder Fri Sep 6 14:26:05 2024
		Build and recreate containers
		- Run Files -
		Name Local Path Docker Path
		> indev /dev /dev
		> istart_iocs /home/htruo /opt/epics/start_iocs
		line all_adl /home/htruo /opt/epics/extra_adl
		Recreate containers

Tools - GUI

- Load and save autosave files
 - Doing this manually can be quite tedious if there is more than one autosave file
 - \circ $\;$ This is confusing for non-EPICS users to do manually

		CIDER			
Machine Components Machine Configuration	Autosave Stop your Dockers before loading. Any changes will need a restart of the containers to see results. The paths inside the previewer default to loading when "Load from specific machine Settings				
Machine Configuration	Securys				
Generate USB Rules	Component:	qd			
Autosave	Timestamp:	Current Save			
	All Components				
	Machine to save to:	am-1124			
	Load from spec	ific machine			
		Save	Load		
	qd - auto_settings.s	sav			
		Previous Save for qd - auto_settings.sav	New Save for qd - auto_settings.sav		
	/home/htruong	/Desktop/cider-dockers/saves/am-1124/autosave/qd/auto_settings.sav	/opt/epics/iocData/qd/autosave/auto_settings.sav		
	Preview				
	XSPRESS3-EXAMPLE:HDF1:SZipNumPixels 16 XSPRESS3-EXAMPLE:HDF1:ZLevel 1 XSPRESS3-EXAMPLE:HDF1:BloscShuffle 1 XSPRESS3-EXAMPLE:HDF1:BloscCompressor 0 XSPRESS3-EXAMPLE:HDF1:BloscLevel 5 XSPRESS3-EXAMPLE:HDF1:StorePerform 1 XSPRESS3-EXAMPLE:HDF1:StorePerform 2 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1 XSPRESS3-EXAMPLE:HDF1:XTLF1 XSPRESS3-EXAMPLE:HDF1 XSPRESS3-EXAMPLE:HDF1 XSPRESS3-EXAMPLE:HDF1 XSPRE		I 1152 channel(s) not connected - or not all gets were successful XSPRESS3-EXAMPLE:HDF1:ChunkSizeAuto 1 XSPRESS3-EXAMPLE:HDF1:NumColChunks 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize2 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize3 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize3 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize4 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize6 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize6 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize6 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize6 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize6 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize8 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize9 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize9 0 XSPRESS3-EXAMPLE:HDF1:ChunkSize9 0		

Tools - GUI

- Other system setup tasks, like generating udev rules for USB devices
 - Very easy to mess up with a typo and very hard to debug

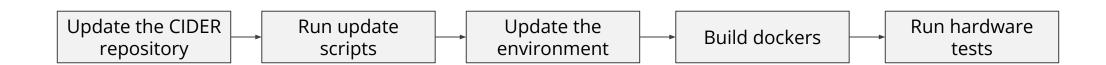
		CIDER	- • ×
Machine Components	ttings	Generate USB Rules	
		hjhgjkhkjijl	✓ Do not generate file
Generate LISB Pulse		ISB-BUS: 1d6b:0002 Linux Foundation 2.0 root hub	
	JSB Alias	Alias	4
Machine Configuration Generate USB Rules USB Alias Autosave USB Information Dev path Id serial Model id Model id database Subsystem Symbolic link Vendor id Generating a udev New Rules:		Run /dev/bus/usb/001/001 /devices/pci0000:00/000:00:14.0/usb1 0000:00:14.0 0000:00:10:10:10:10:10:10:10:10:10:10:10	

Deploying Updates



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Goal: Offline Updates

Customer Restrictions

- No internet access allowed
 - Cannot rebuild docker images that access internet (e.g. assemble_synapps)
- File size restrictions
 - Cannot export 7+ docker images that are 2-3 GB each
 - Cannot put all contents into one giant docker image



Goal: Offline Updates

Expected Procedure

- Files
 - Base docker image
 - Contains all shared online dependencies like synApps, Linux packages, etc
 - CIDER
 - Contains environment files, configuration files, and helper scripts
 - GUI folder
 - Generated by pyinstaller, making python dependencies portable
- Procedure



Potassium distribution in flowers acquired on Sigray AttoMap

This includes CIDER, EPICS, and non-EPICS takeaways.



The Bad

- CIDER is difficult to develop with
 - The file structure can be confusing, and developers need to know what files are in the IOC submodule and what files are overwritten by CIDER
 - Having a branch per machine can lead to more toil if changes are frequently made after PRs are merged
 - Perhaps a file structure refactor with local config files and a version controlled configuration repository will improve this
- Having one environment file makes it unclear what variables correspond to what docker service
 - This makes it hard to know what environment variables to define or remove when adding/removing docker services
 - Hopefully the addition of **multiple environment files** in docker compose or just plain old Python to generate the environment files and machine compose files
- Storing configuration files in the same repository is not sustainable
 - Repository size will keep growing as we build more systems
 - Plan to move them into their own repository or make them local



The Bad

- Autosave can be unreliable
 - Turning off power to devices can lead to some PVs being wiped in autosave
 - Some PVs will randomly reset when the IOC or computer restarts
- MEDM is not very dynamic, and it can be hard to make modifications
- EPICS can be confusing to develop with (requires training) and debug
- Some of these issues may totally be due to my insufficient knowledge of EPICS!



The Good

- Reuse an IOC repository as much as possible to make it easier to propagate changes to all machines
 - Achieved by moving as many build-time settings to run-time as possible to avoid requiring recompilation (and thus a new docker image)
 - Use environment variables in sequencer, st.cmd, .db
 - This also makes testing faster and easier, since we can heavily test the base IOC and sprinkle tests for the runtime settings
- Migration scripts have helped with ensuring machine settings are not lost during updates, even if the configuration files have changed structurally
- Keeping configuration files in version control is great!
 - Track why changes were made, rollback to an older version, diff files, etc
- ADAravis is great for creating new IOCs for GenICam-compatible detectors!
 - Doesn't always work right off the bat



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The Good

- Docker and docker compose has some helpful features that allows us to have a simpler file structure
 - multiple build contexts
 - Can organize things in terms of logical categories rather than in terms of docker images
 - Avoids duplication of files that belong in multiple docker images
 - The docker compose file itself can use environment variables
 - Useful for storing all env vars in one file and propagating them
 - (Future) The **include** top-level element
 - Allow us to define dependencies without:
 - Duplicating docker service definitions
 - Defining service definitions in the same docker compose file



